



Complex resonant ice shelf vibrations

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Australian Government
Australian Research Council



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Australian Antarctic Division

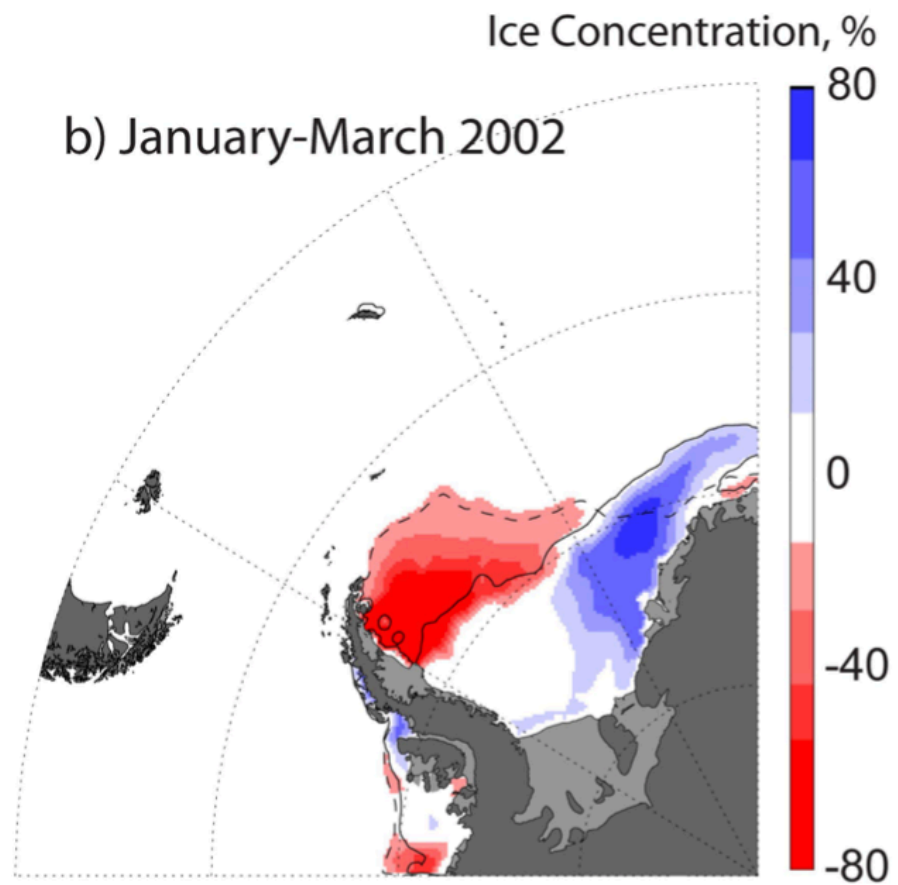
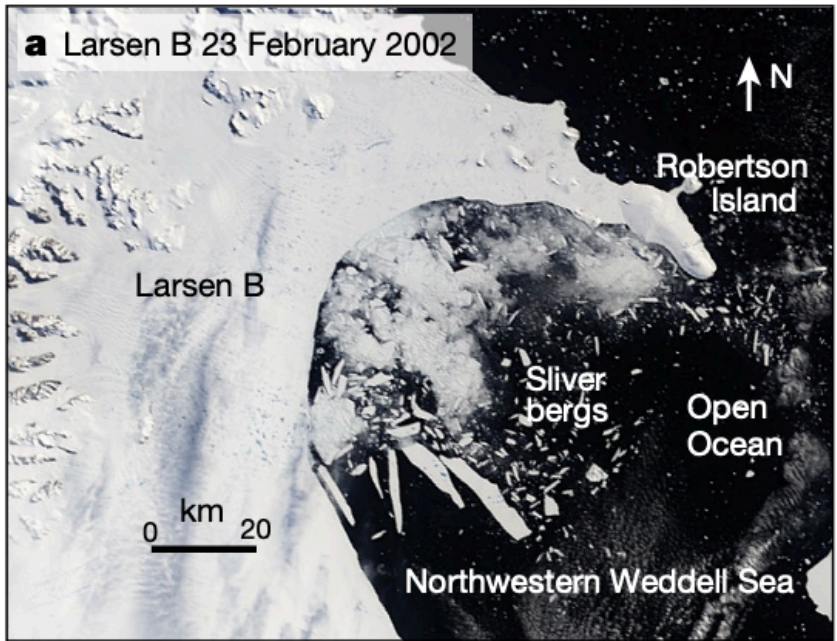


@KOZWaves

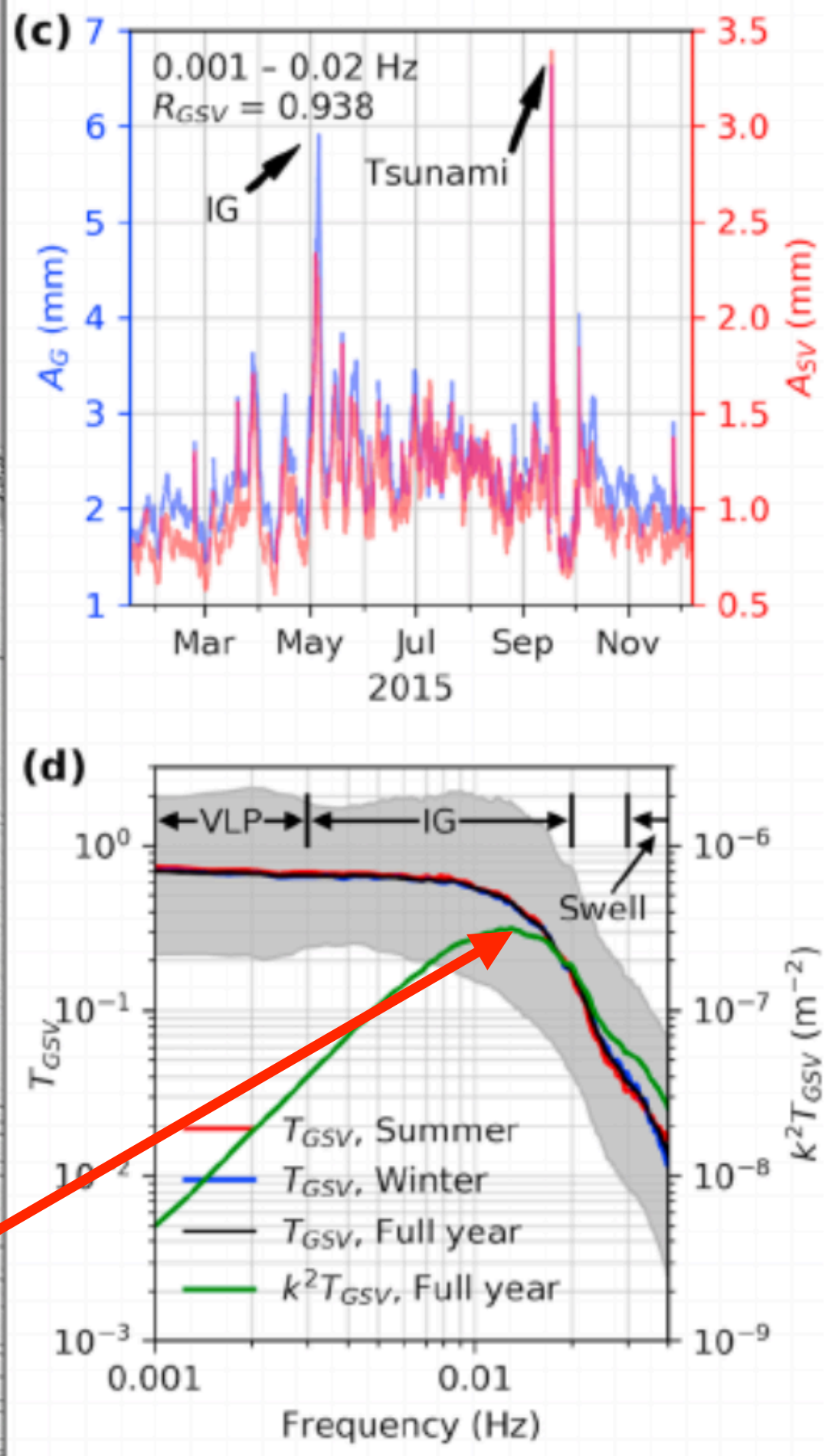
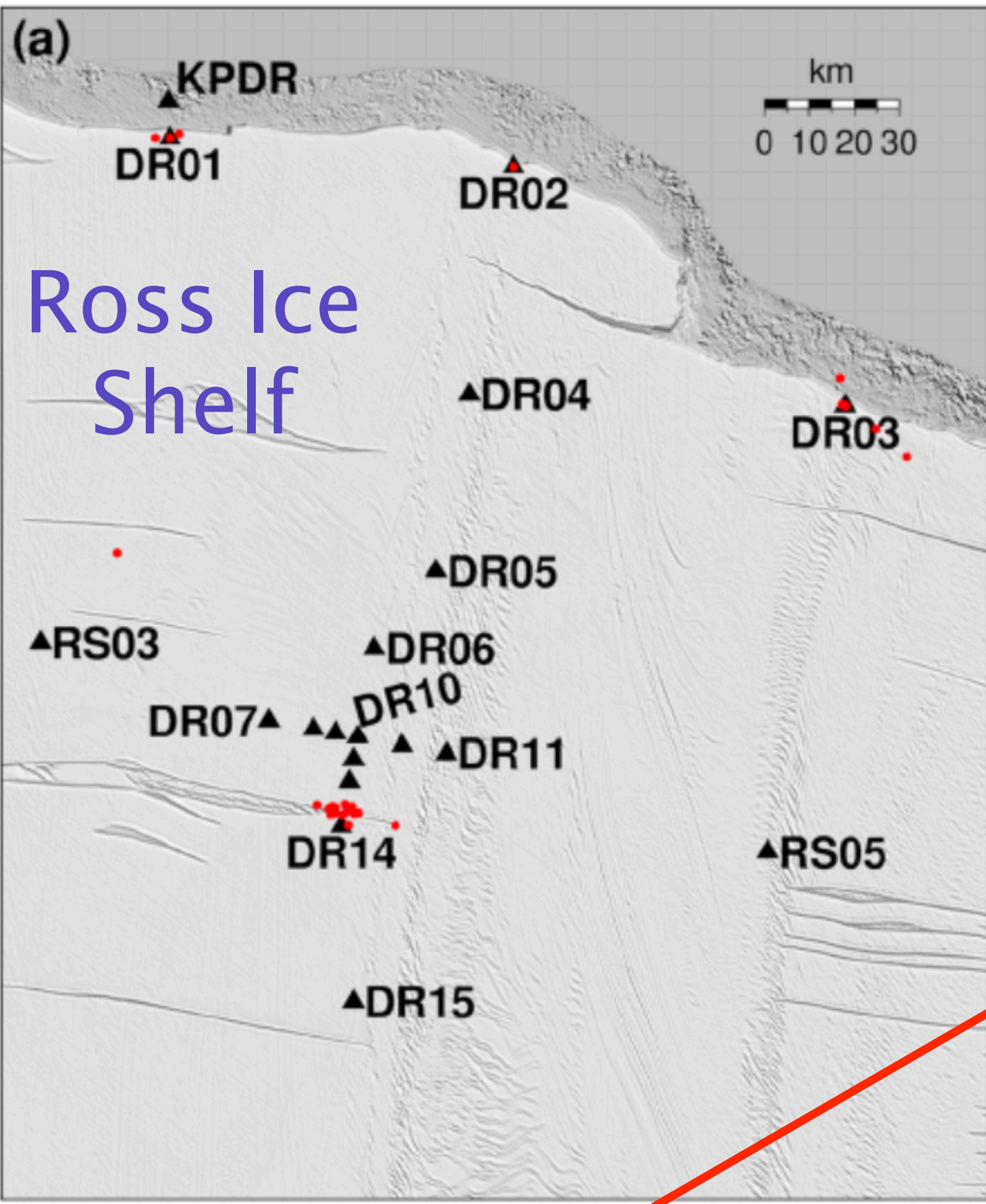
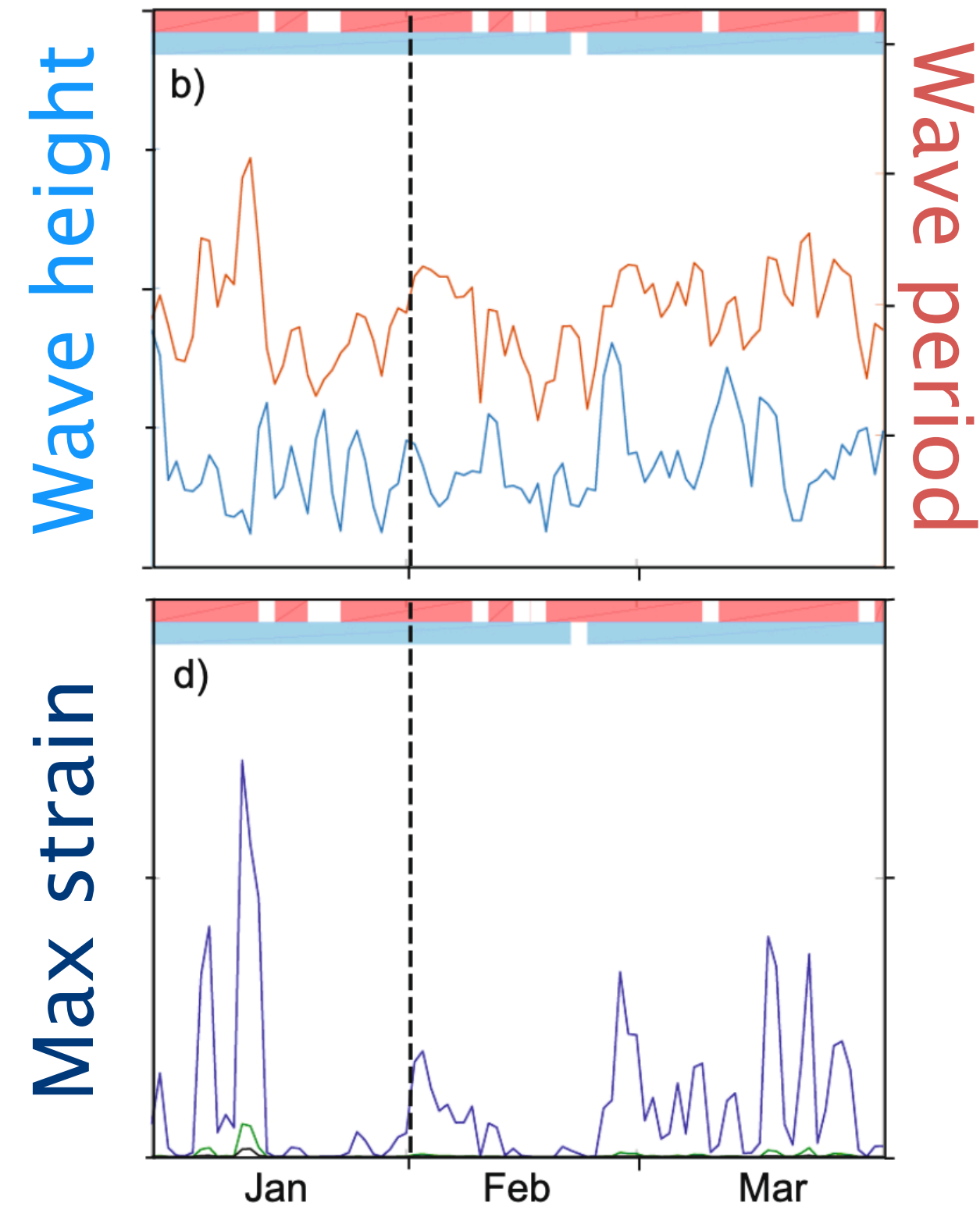


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Motivation: wave-induced shelf vibration measurements



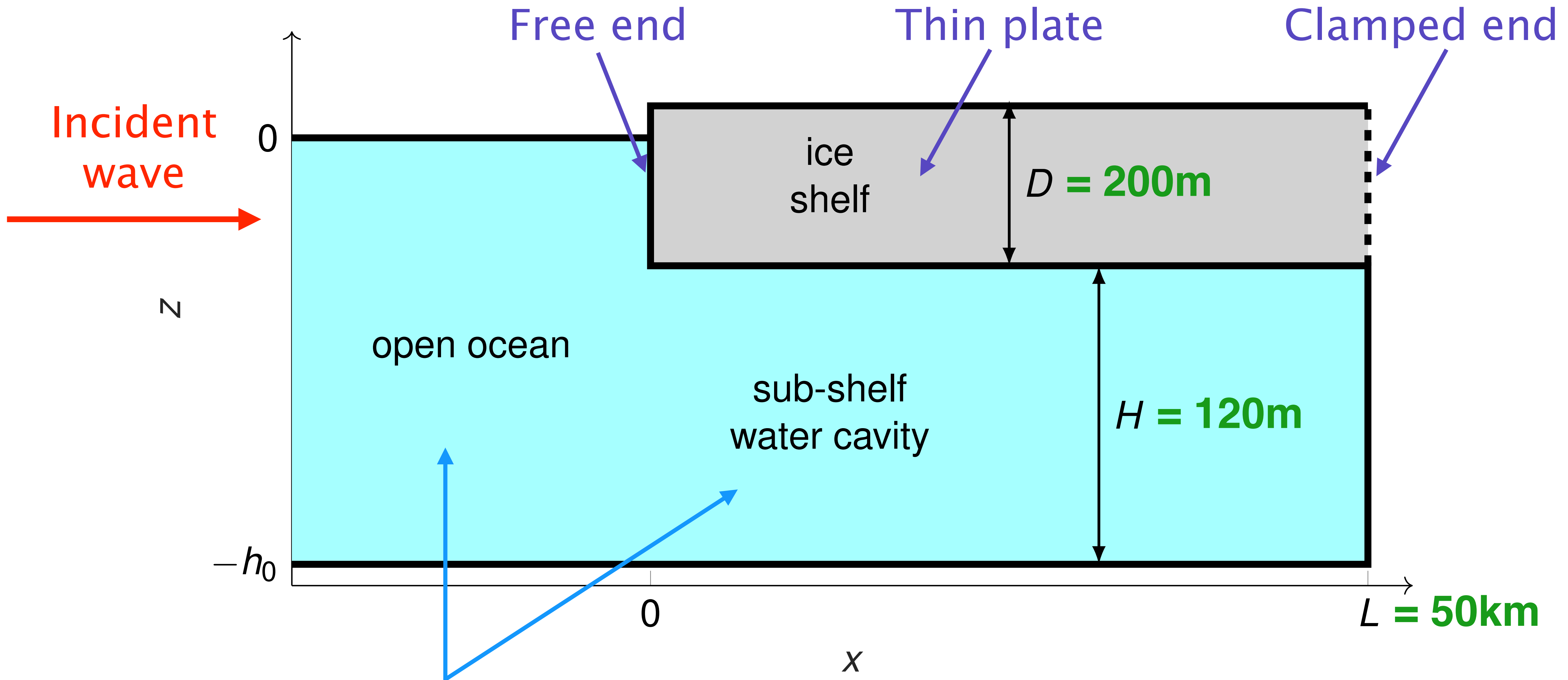
Massom et al, Nature, 2018



Max strain at period 50–100s or $\omega/\pi = 0.02\text{--}0.04$ Hz

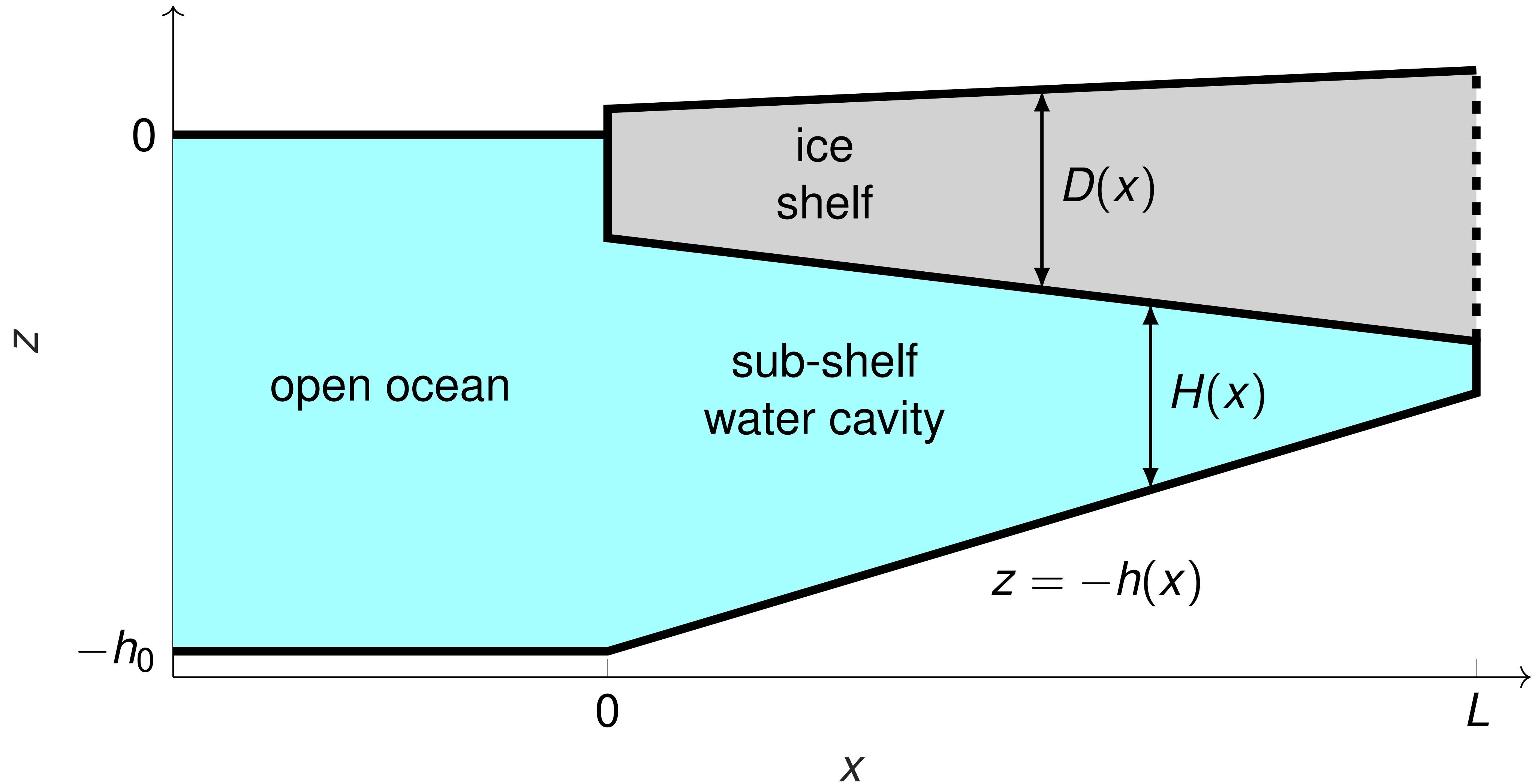
Chen et al, Geophy Res Lett, 2019

Standard model



Potential flow: shallow water or finite depth

Model with thickening shelf and shoaling seabed



Governing equations

Single-mode approximation

- Water velocity field is real part of

$$\operatorname{Re}\{\phi(x, z) e^{-i\omega t}\} \quad \text{where} \quad \begin{cases} \omega \in \mathbb{R}^+ & \text{angular velocity (prescribed)} \\ \phi \in \mathbb{C} & \text{velocity potential (unknown)} \end{cases}$$

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- In open ocean

$$\phi(x, z) \approx \varphi_0(x) \frac{\cosh k(z + h_0)}{\cosh(k h_0)} \quad \text{where} \quad k \tanh(k h_0) = \sigma \equiv \frac{\omega^2}{g}$$

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- In cavity

$$\phi(x, z) \approx \varphi(x) \frac{\cosh \kappa(z + h)}{\cosh(\kappa h)} \quad \text{where} \quad (1 - \sigma d + \Gamma \kappa^4) \kappa \tanh(\kappa H) = \sigma$$

Governing equations

Depth averaged equations

- In open ocean, set

$$\varphi_0(x) = A_{\text{inc}} \left(e^{i k x} + R e^{-i k x} \right)$$

where A_{inc} is incident amplitude (prescribed), and $R \in \mathbb{C}$ is the reflection coefficient (unknown).

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- In shelf/cavity, solve ODE system

$$(a \varphi')' + b \varphi + \sigma \zeta = 0 \quad \text{and} \quad (1 - \sigma d) \zeta + \mathcal{L}\{\zeta\} - \varphi = 0$$

with known coefficients $a(x)$ and $b(x)$, and where $\text{Re}\{\zeta(x) e^{-i \omega t}\}$ is the shelf vibration (unknown).

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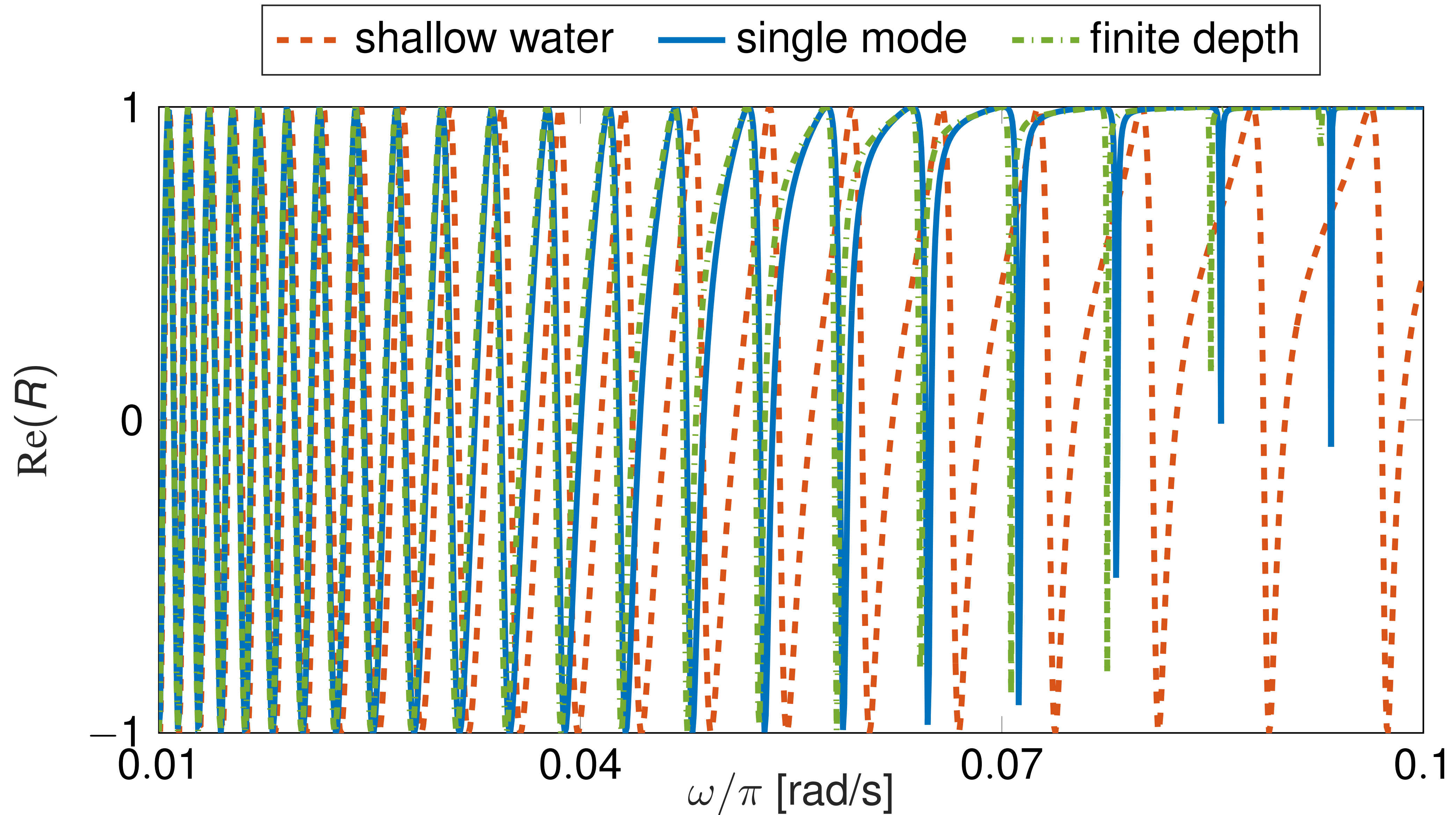
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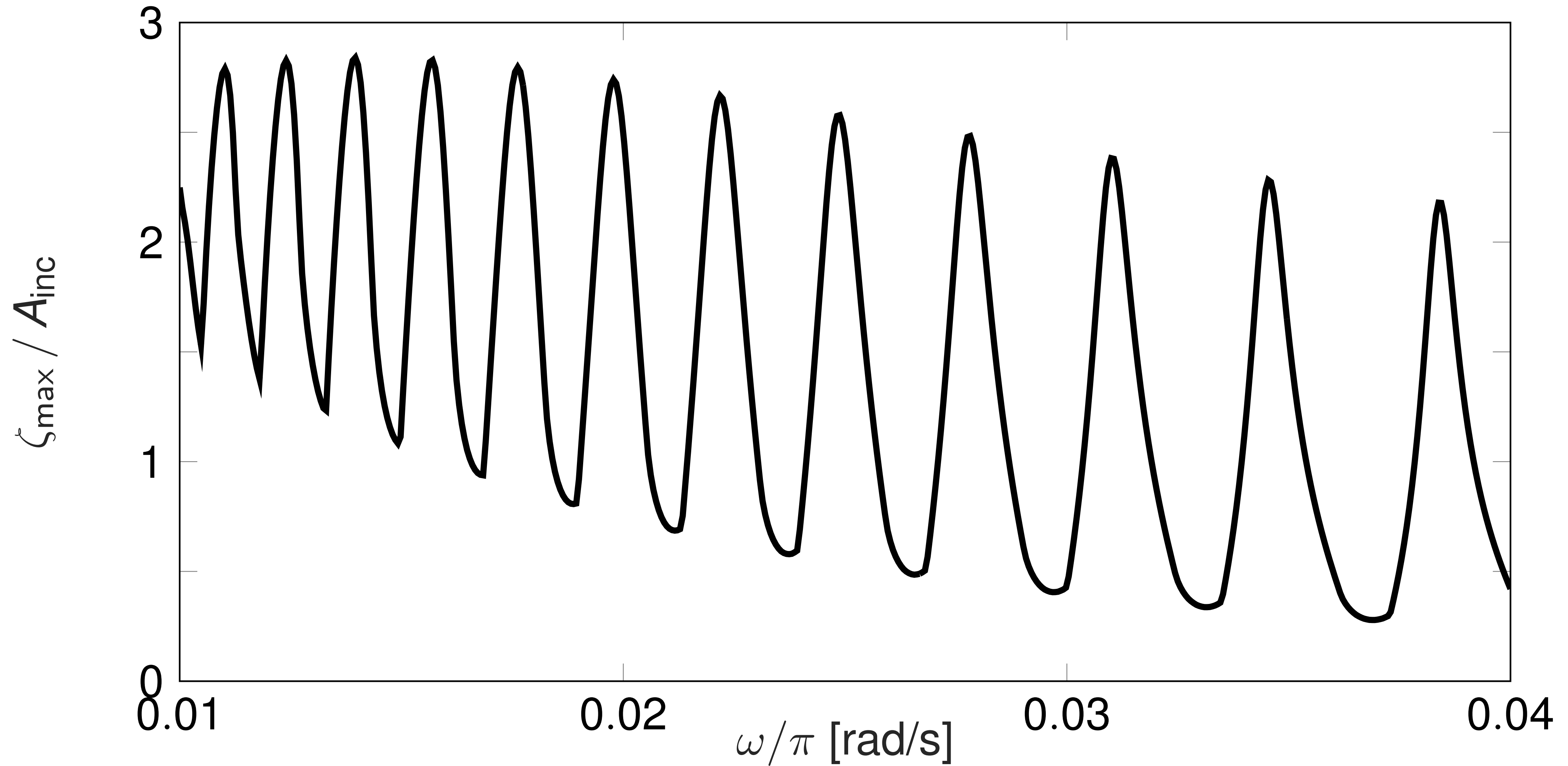
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- + “jump conditions” at $x = 0$, i.e. depth averaged continuities.
- + shelf end conditions, i.e. free at $x = 0$ and clamped at $x = L$.

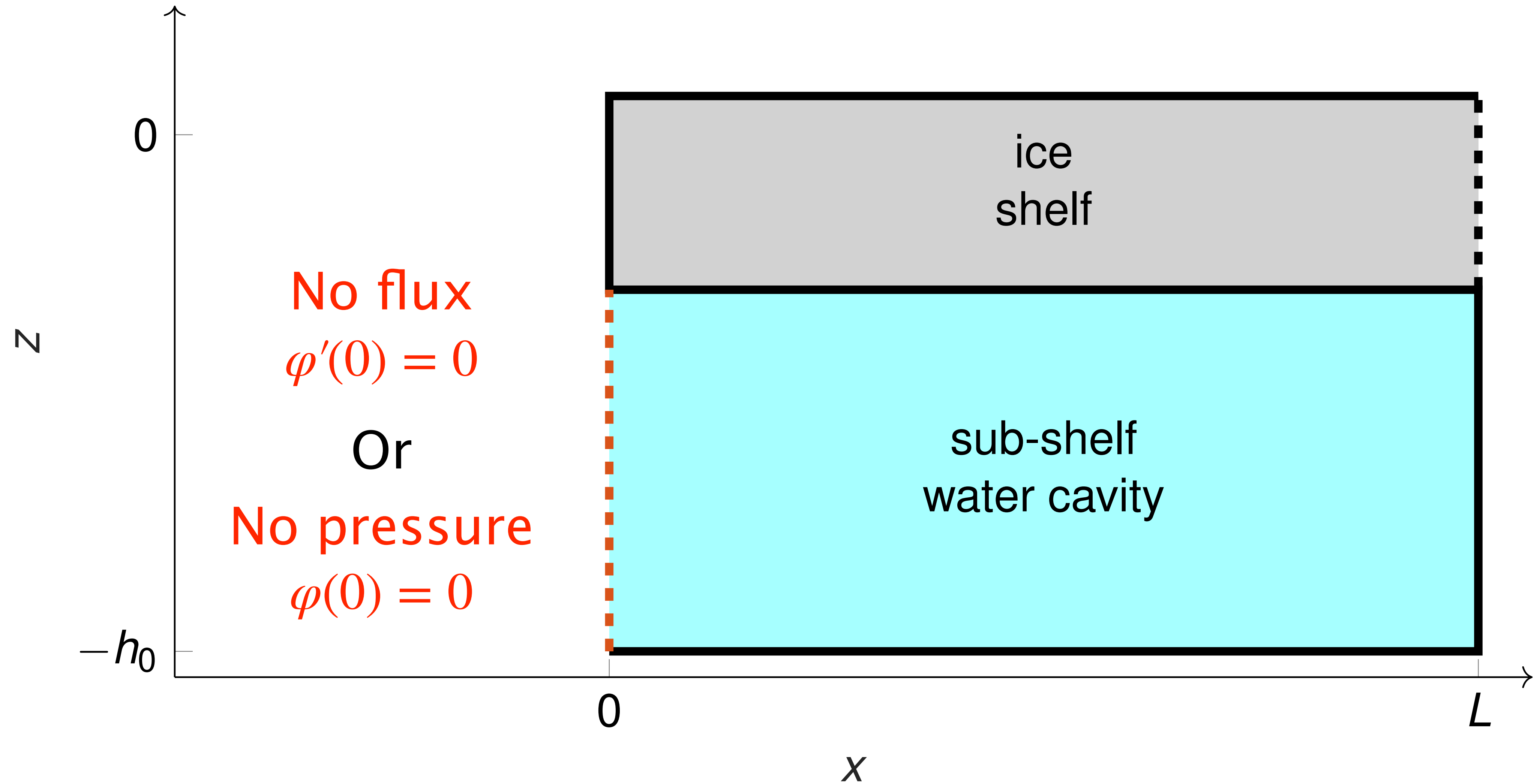
Accuracy of single-mode approximation (uniform geometry)



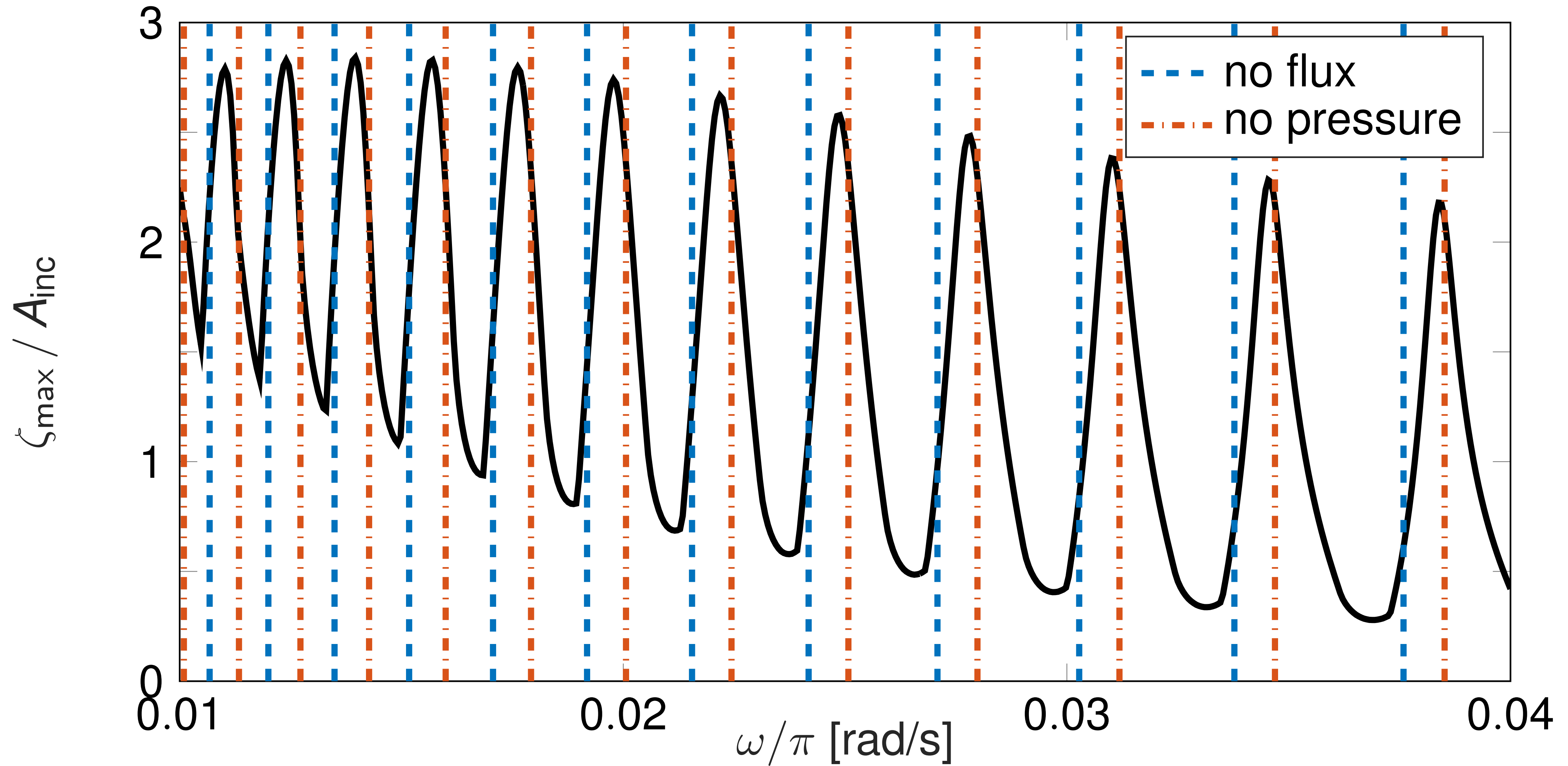
Maximum shelf displacement: Uniform geometry



Uncoupled problems



Maximum shelf displacement: Uniform geometry



Jump conditions

- Can be expressed as

$$c_1 \left(\frac{\varphi'(0)}{\kappa} \right) + i c_2 \varphi(0) = 2 i k A_{\text{inc}}$$

and $c_1 \left(\frac{\varphi'(0)}{\kappa} \right) - i c_2 \varphi(0) = -2 i k R A_{\text{inc}}$

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- Resonance if non-zero solution for $A_{\text{inc}} = 0$, i.e.

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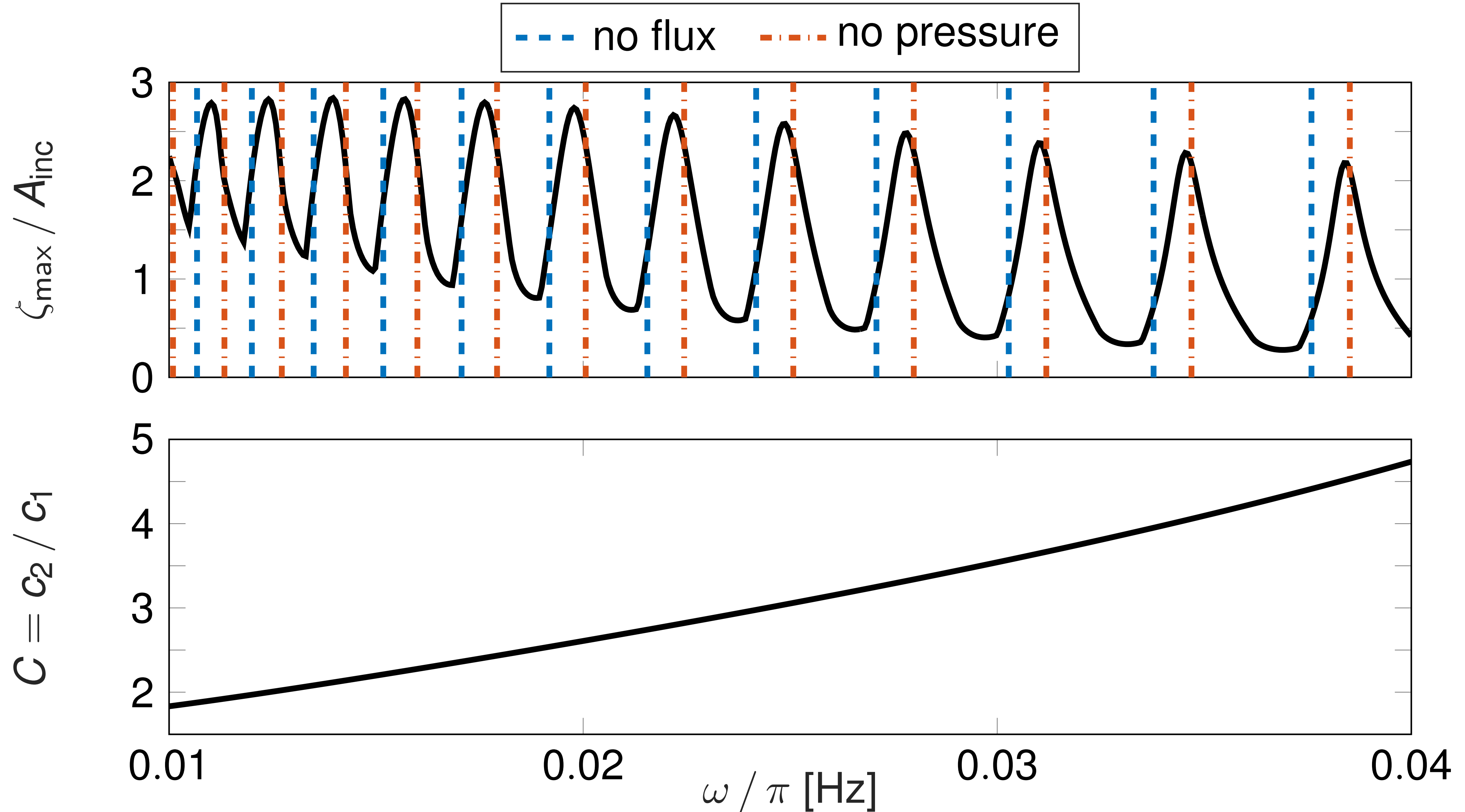
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$$\frac{\varphi'(0)}{\kappa} + i C \varphi(0) = 0 \quad \text{where} \quad C = \frac{c_2}{c_1}$$

- Closer to **no-flux condition** if $C \ll 1$ and **no-pressure condition** if $C \gg 1$.

Maximum shelf displacement: Uniform geometry



Complex resonances

- Resonance occurs at $\omega = \omega_m \in \mathbb{C}$ and $\zeta(x) = \zeta_m(x)$ ($m = 1, 2, \dots$).
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 - Increases computational expense.
- Uncoupled eigenfrequencies $\in \mathbb{R} \Rightarrow$ easy/cheap to calculate.
- Complex frequencies $\in \mathbb{C} \Rightarrow$ difficult/expensive to calculate.

Homotopy method

- Find ω_m from $\det(\mathcal{M}) = 0$, where \mathcal{M} is 6×6 matrix

$$\mathcal{M}(\omega) = \begin{pmatrix} \mathcal{I} & -\mathcal{R}_+(\omega) \mathcal{E}(\omega) \\ -\mathcal{R}_{\text{Id}}(\omega) \mathcal{E}(\omega) & \mathcal{I} \end{pmatrix}$$

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- Uncoupled eigenfrequencies satisfy similar relation, but with $\mathcal{R}_+ \mapsto \mathcal{R}_f$ or \mathcal{R}_p :

$$\mathcal{R}_f = \mathcal{R}_+ + \mathcal{T}_- (1 - \mathcal{R}_-)^{-1} \mathcal{T}_+ \quad \text{and} \quad \mathcal{R}_p = \mathcal{R}_+ - \mathcal{T}_- (1 + \mathcal{R}_-)^{-1} \mathcal{T}_+$$

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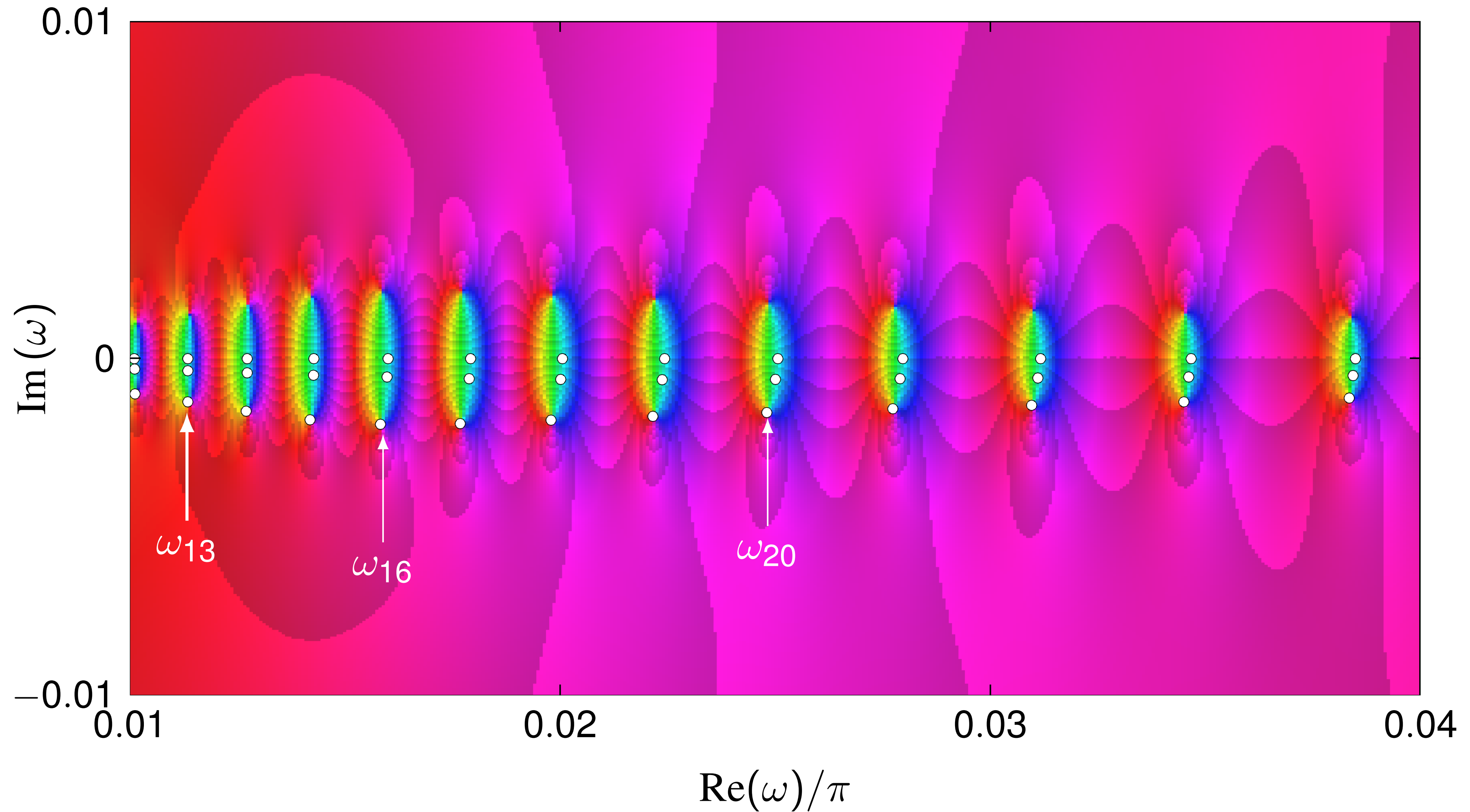
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- Construct homotopy in which $\mathcal{R}_+ \mapsto \mathcal{R}_{\hbar}$:

$$\mathcal{R}_{\hbar} = \mathcal{R}_+ + (1 - \hbar) \mathcal{T}_- (1 - \mathcal{R}_-)^{-1} \mathcal{T}_+ \quad \text{or} \quad \mathcal{R}_+ - (1 - \hbar) \mathcal{T}_- (1 + \mathcal{R}_-)^{-1} \mathcal{T}_+$$

- Start with eigenfrequencies and vectors for uncoupled problem (no flux or no pressure) and solve iteratively, e.g. for $\hbar = 0, 0.1, 0.2, \dots, 1$.

Reflection coefficient in complex frequency space



Blaschke product

- Note that

$$|R|^2 = 1 \quad \text{for } \omega \in \mathbb{R} \quad \text{i.e. energy conservation}$$

$$\text{and } R(\bar{\omega}) = |R(\omega)|^{-1} e^{i \arg\{R(\omega)\}}.$$

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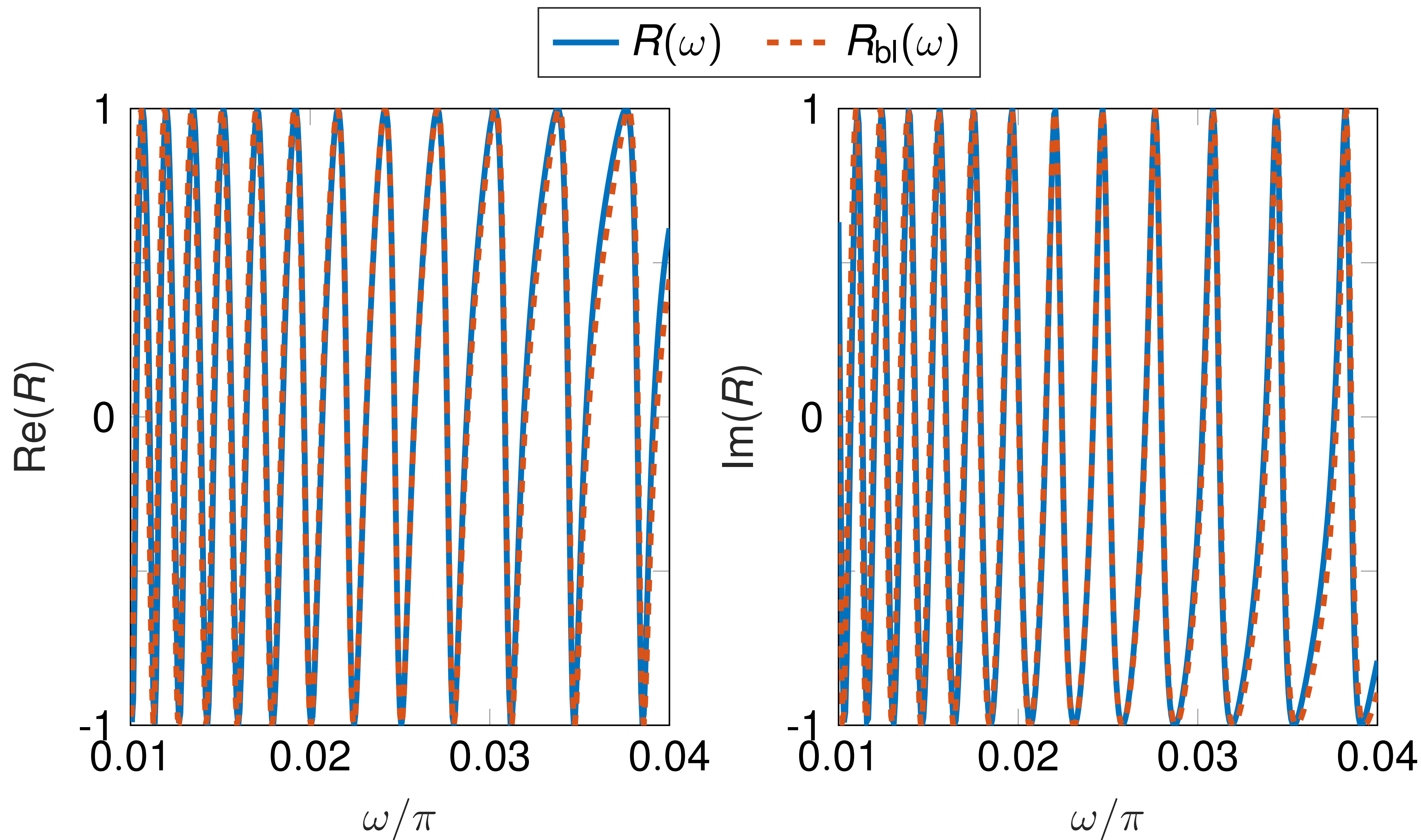
- Define

$$R_{\text{bl}}(\omega) = \prod_{n=1}^{\infty} r(\omega : \omega_n) r(\omega : -\bar{\omega}_n)$$

where

$$r(\omega : \varpi) = \frac{\omega - \bar{\varpi}}{\omega - \varpi}.$$

Blaschke product



Incident wave packets and singularity expansion method

Gaussian incident packet

- Defined by the Fourier transform (in k)

$$\mathcal{F}\{u_{\text{inc}}\} = \frac{1}{\pi} \sqrt{2\beta} e^{-\beta(k-k_0)^2}$$

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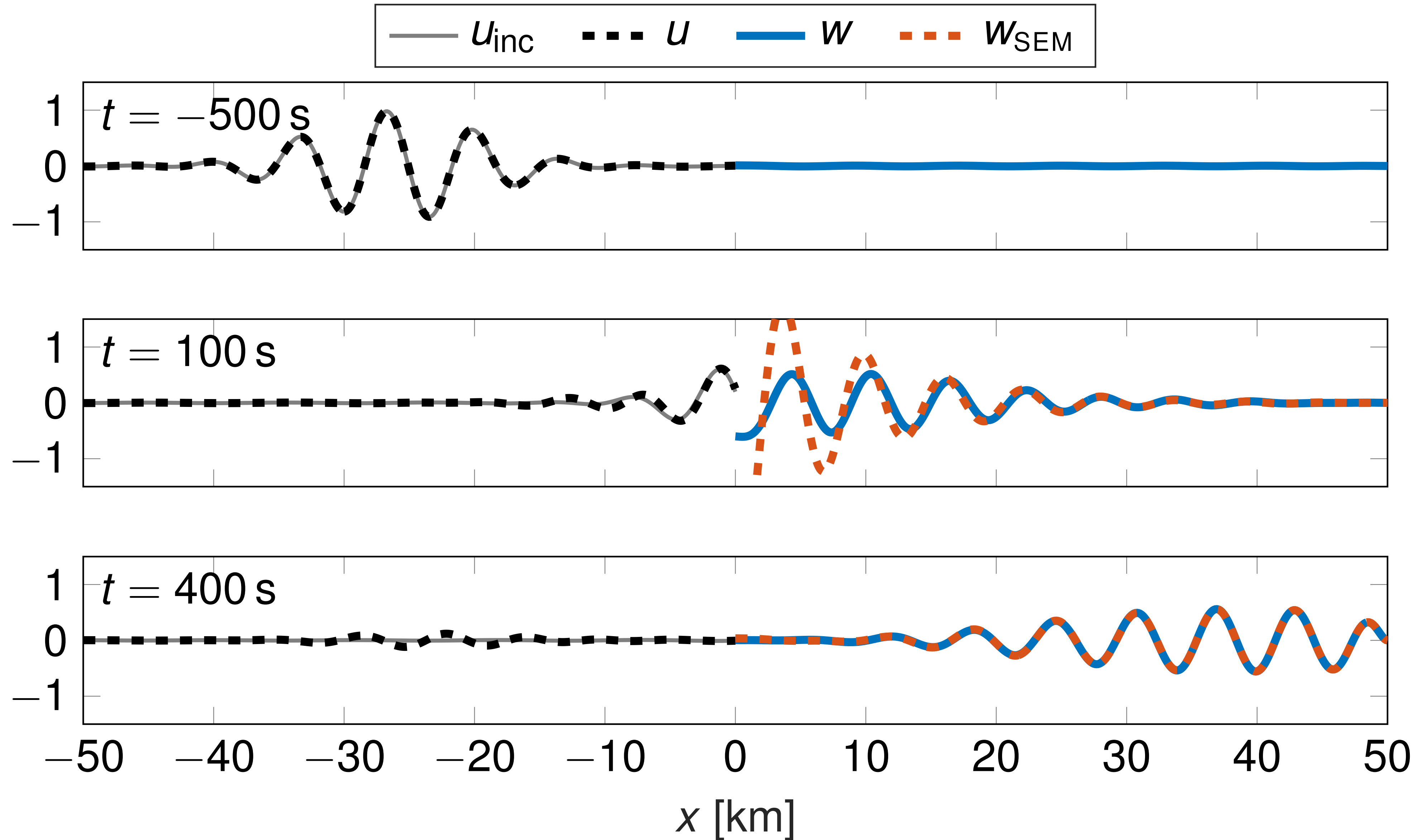
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Singularity expansion method

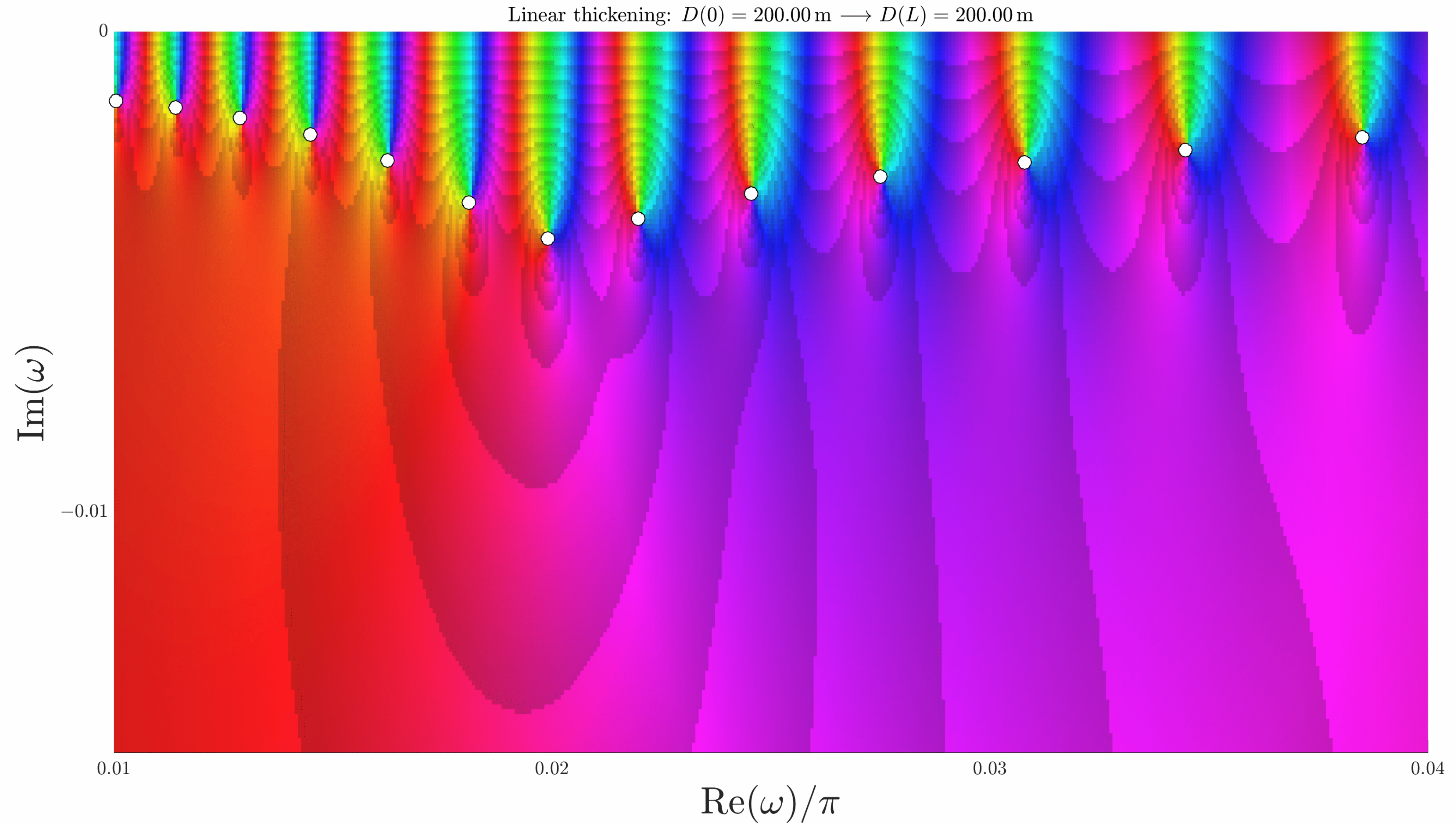
- For long times, the shelf displacement

$$w(x, t) \sim w_{\text{SEM}}(x, t) = \sum_{n=1}^{\infty} w_n(x, t) \quad \text{where} \quad w_n = \text{Re}\{A_n e^{-i\omega_n t}\}.$$

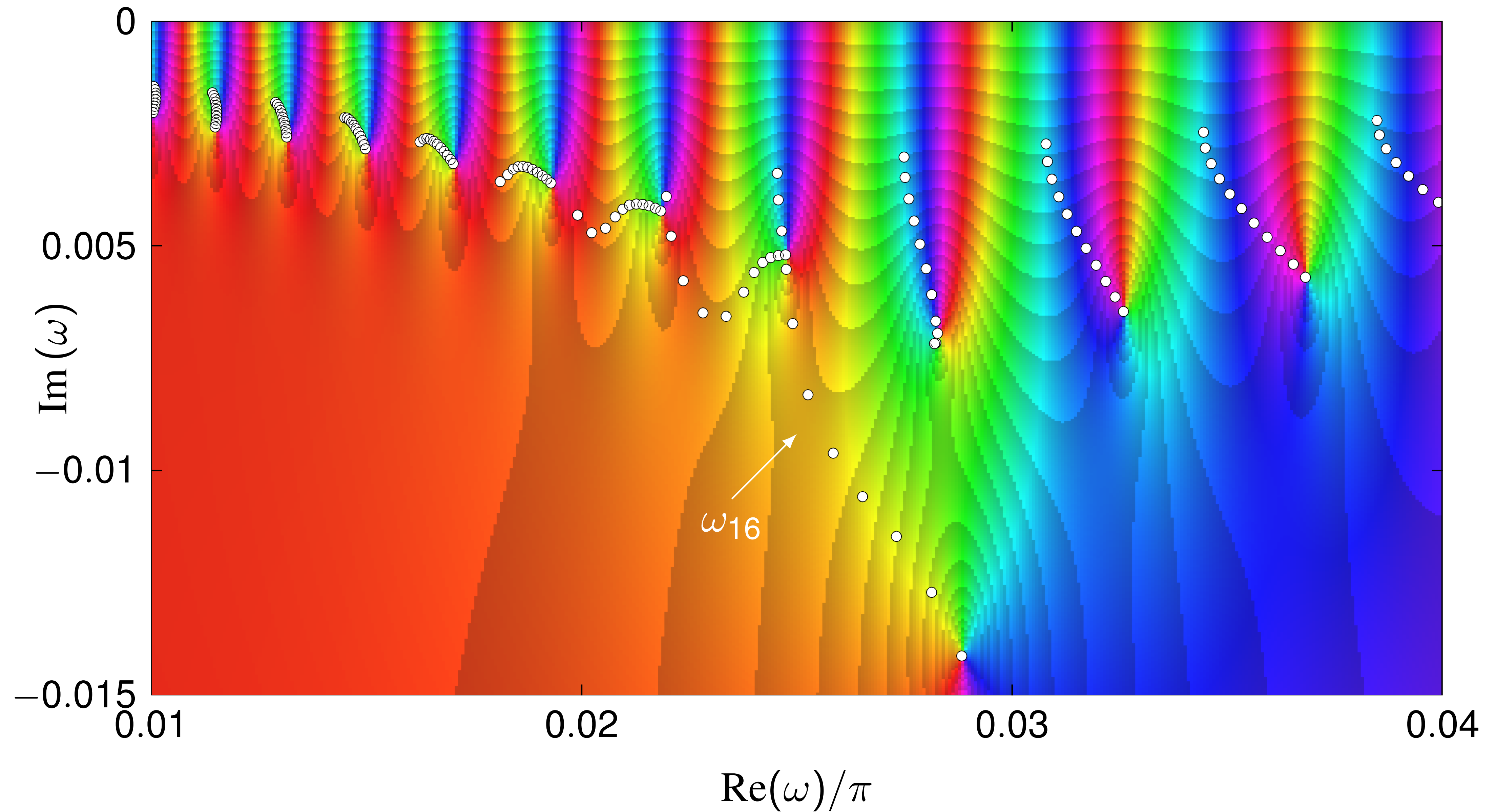
Example time domain simulation



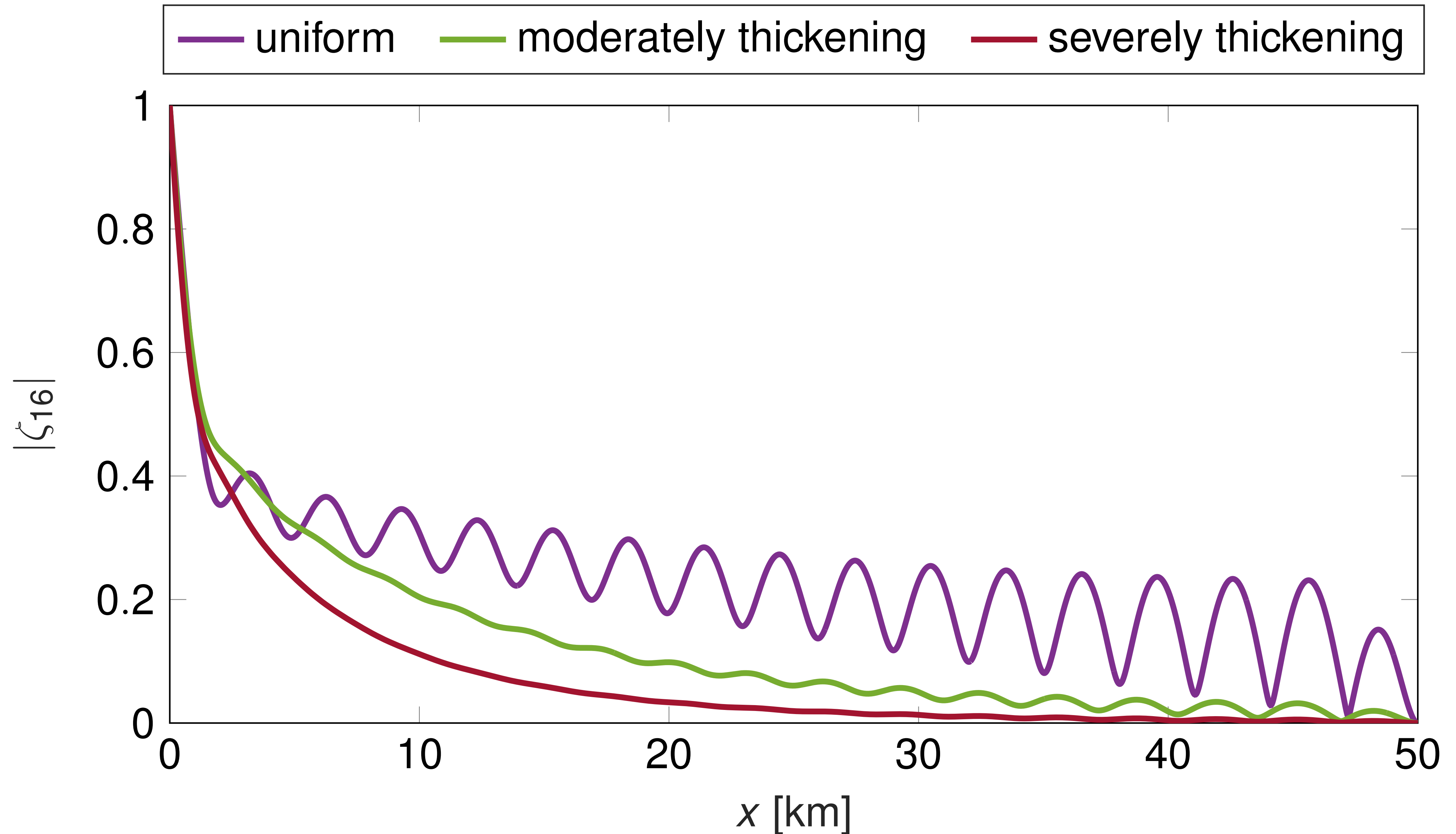
Thickening shelf: $R(\omega)$



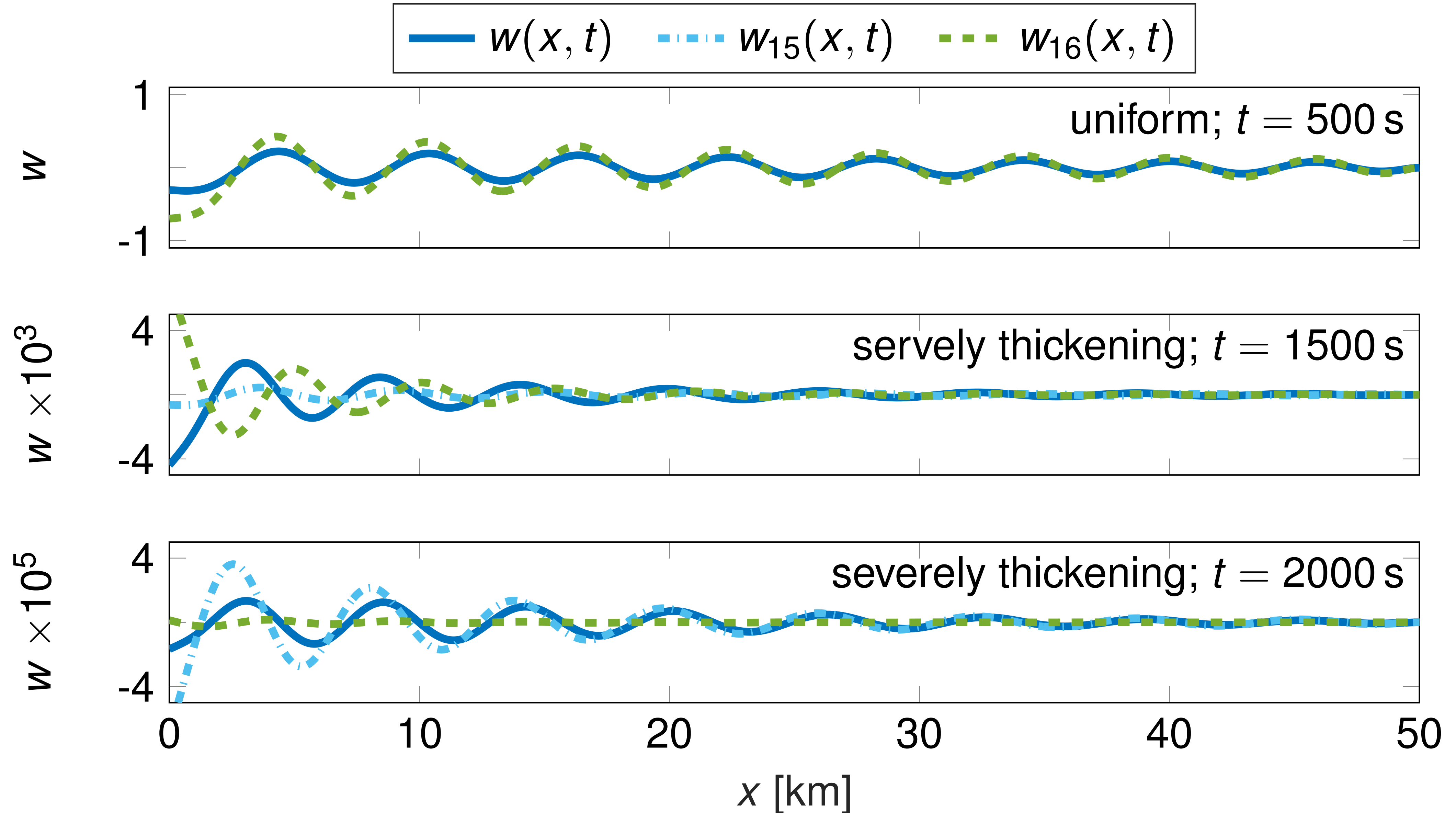
Thickening shelf: $R(\omega)$



Thickening shelf: complex resonant modes



Example time domain simulation



Summary

Methods

- Efficient method for non-uniform geometries.
- Homotopy method to find complex resonances.

Complex reonances

- Approximate frequency-domain solutions via Blaschke product.
- Capture long-time behaviour of transient solutions.

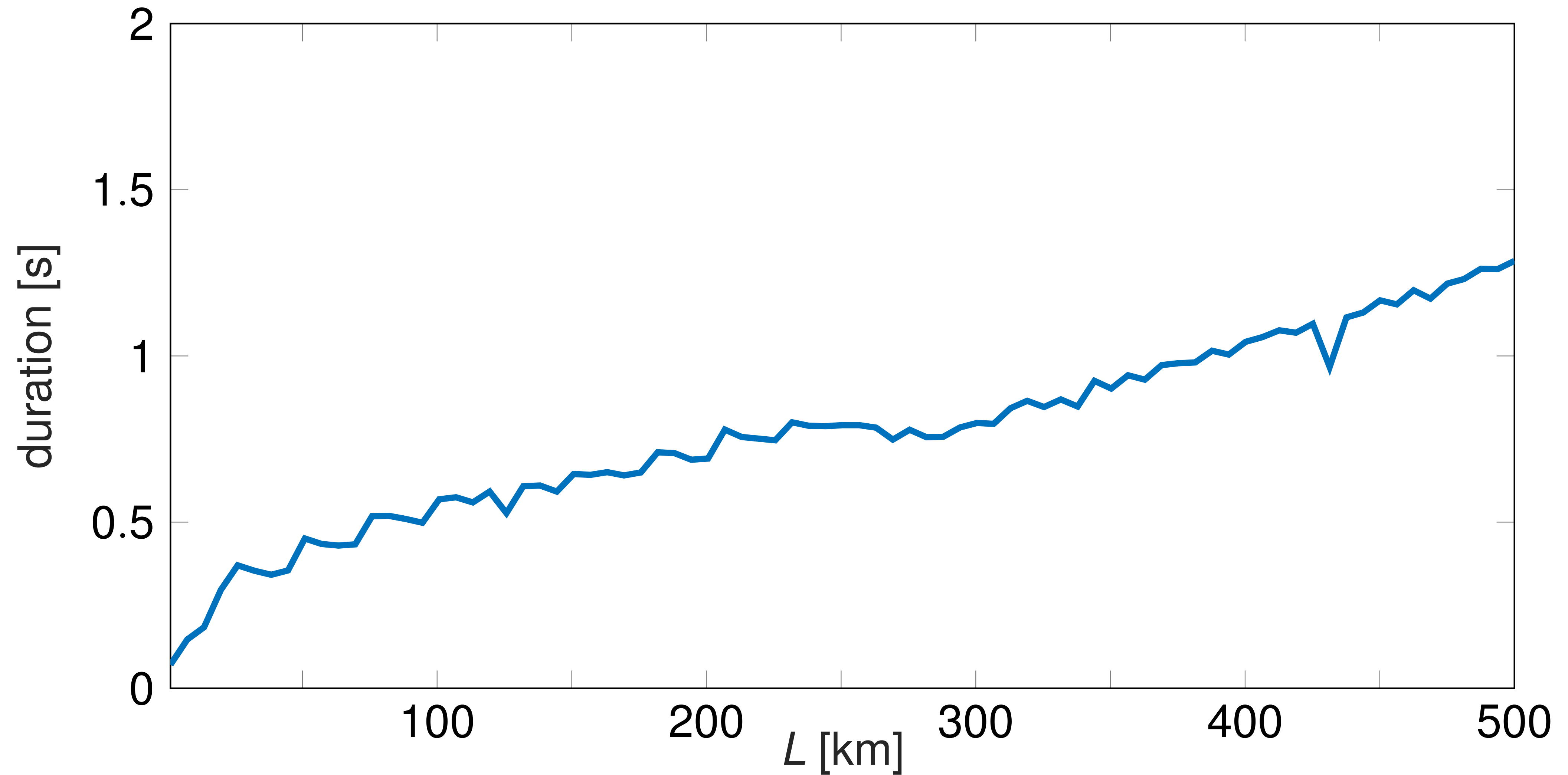
Thickening shelf

- Can prevent mid-range-frequency resonances from being excited.

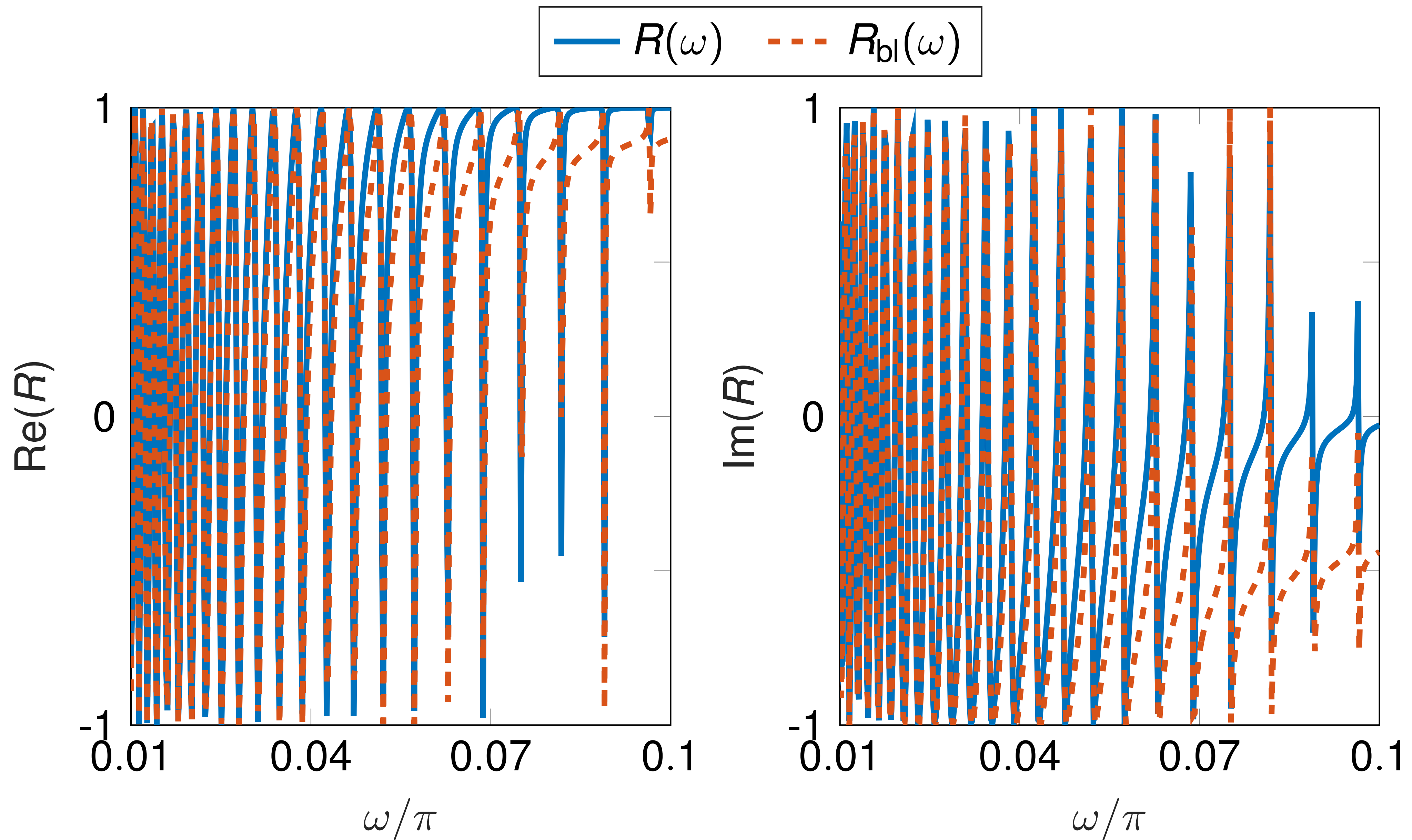


Coda

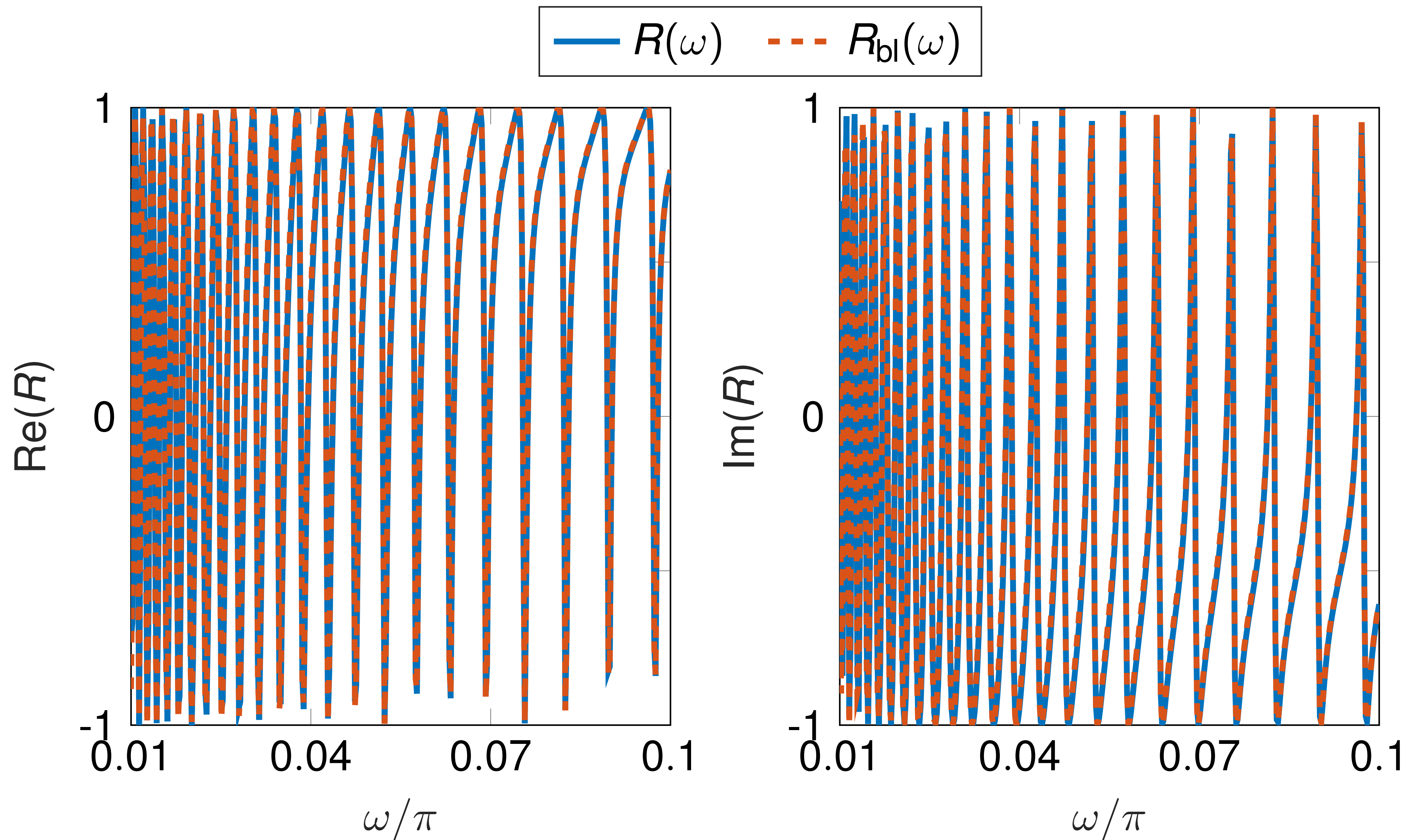
Efficiency of step approximation for varying geometry



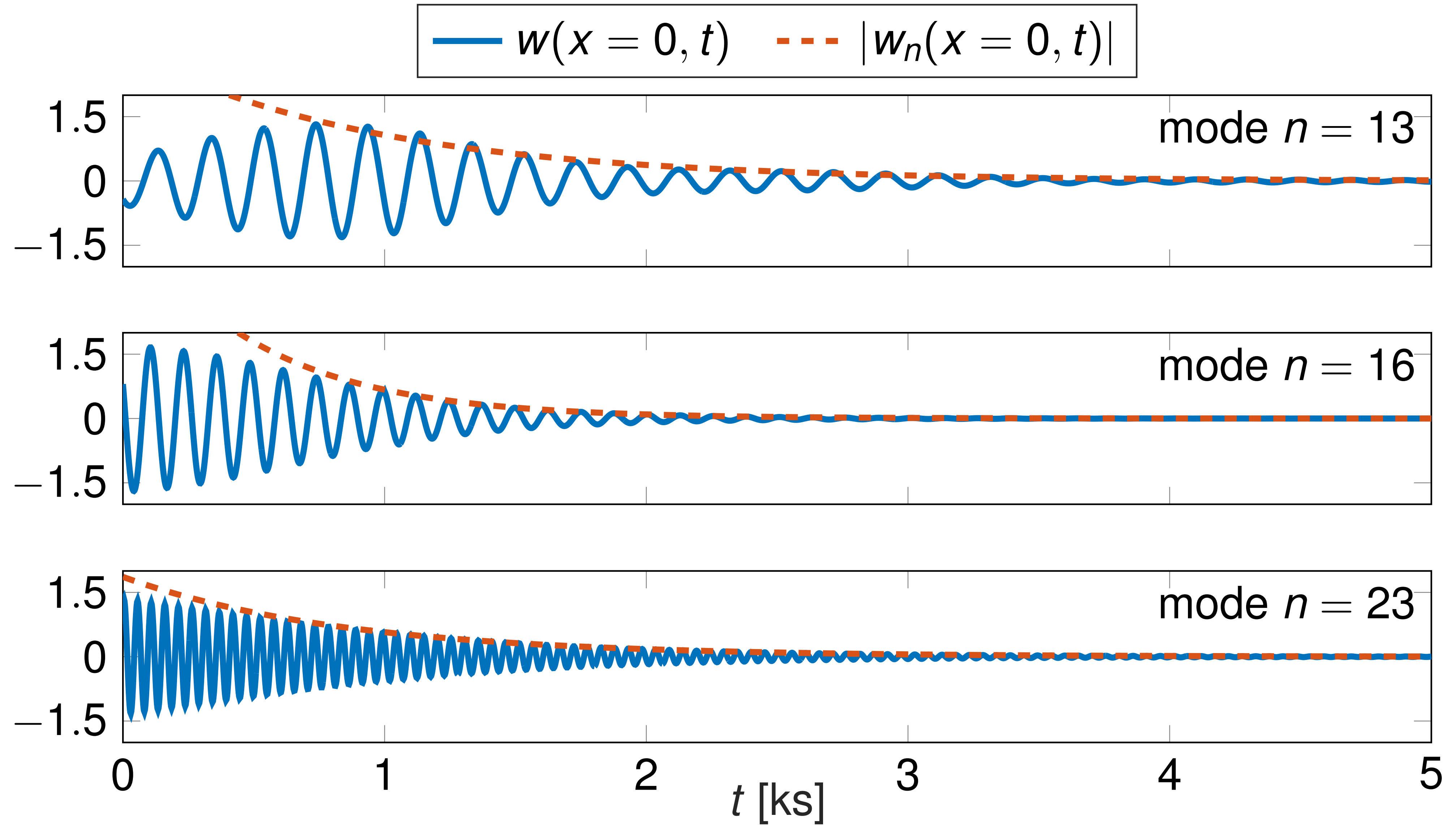
Blaschke product: Extended frequency range



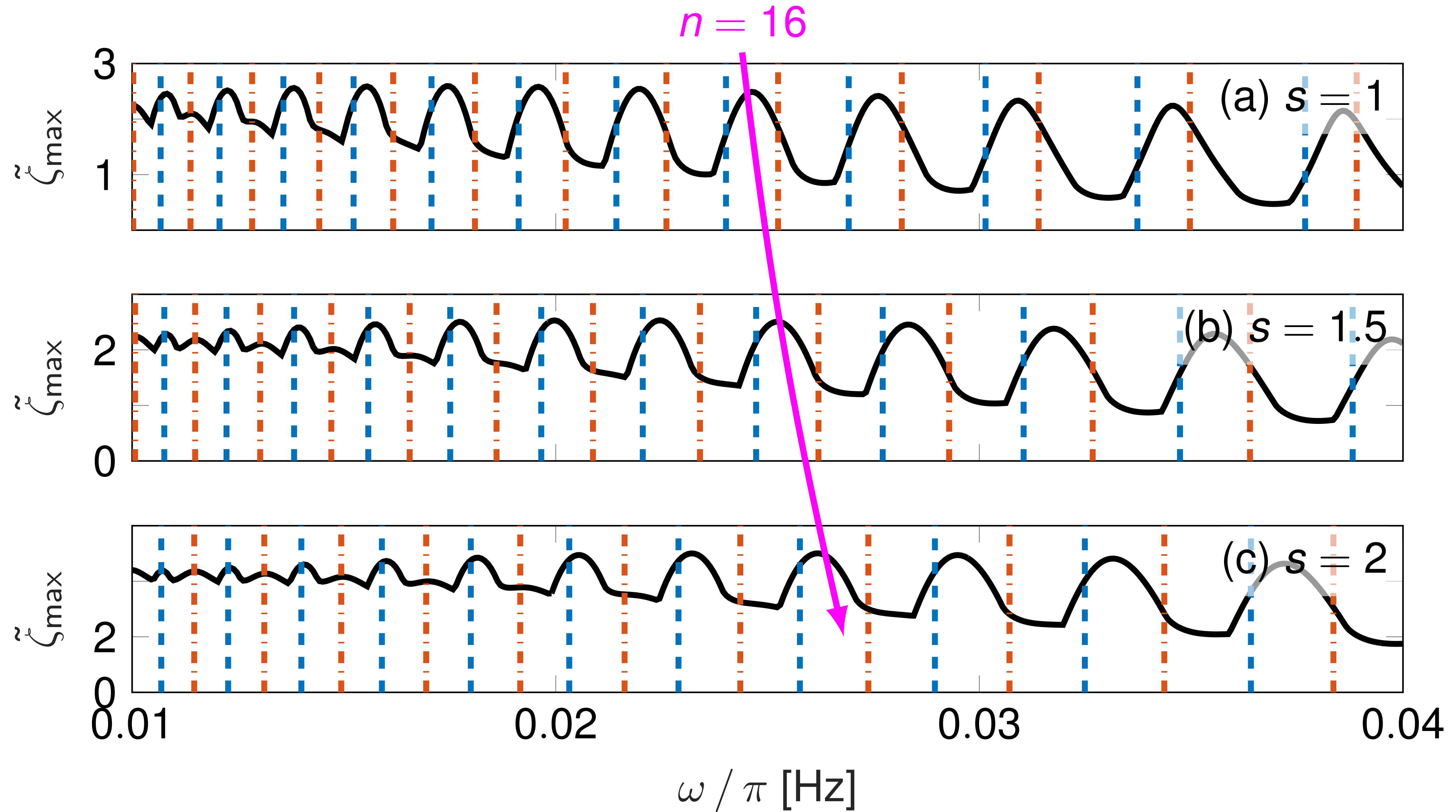
Blaschke product: Shallow-water approximation



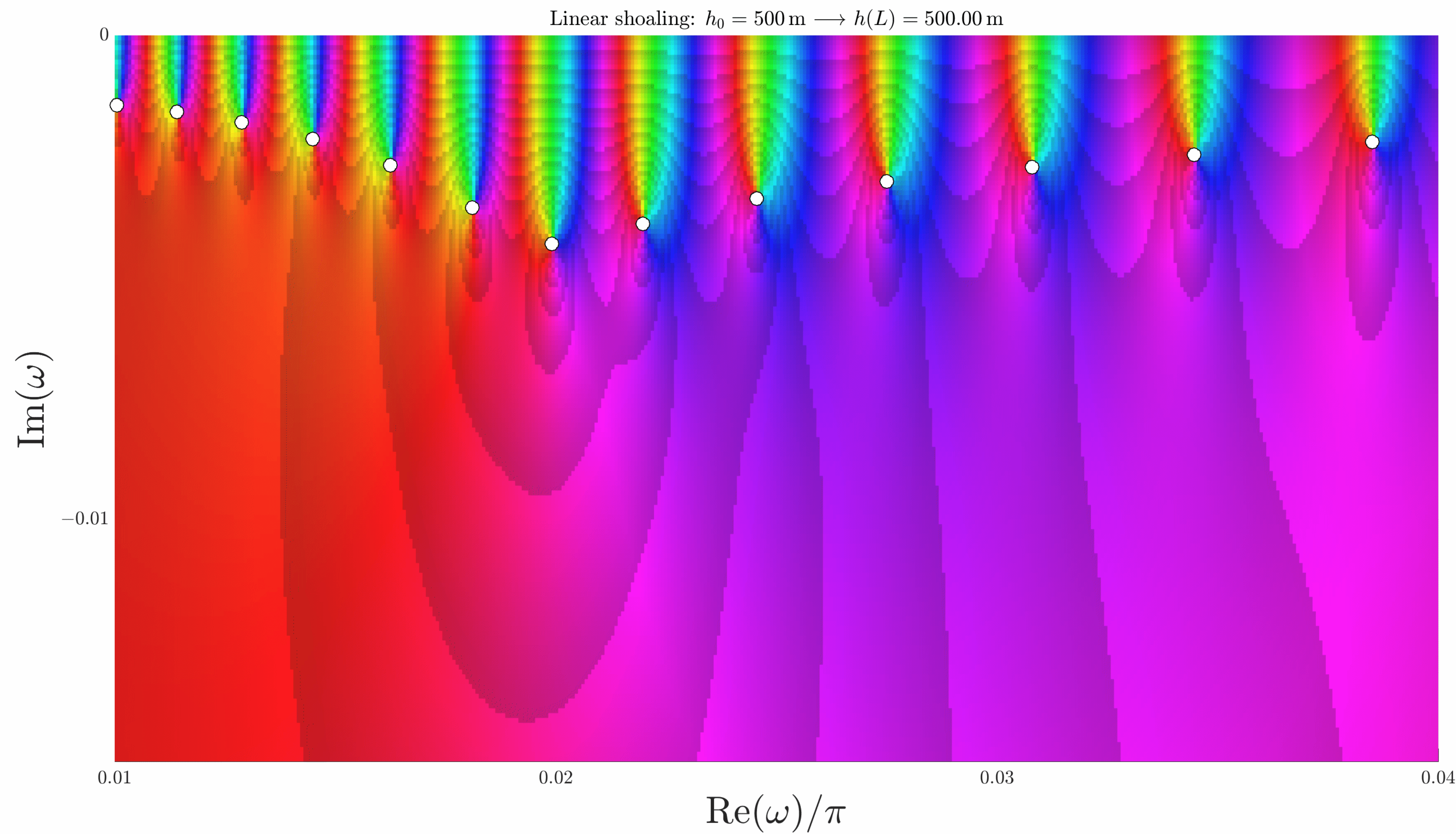
Resonant lifetimes



Maximum shelf displacement: Thickening shelf



Shoaling bed: $R(\omega)$



Thickening shelf: complex resonant modes η_n

